https://ntrs.nasa.gov/search.jsp?R=19700008098 2018-07-23T23:50:32+00:00Z

CORY

NASA CR 107840

17403

A RAPIDLY CONVERGING TRIANGULAR PLATE ELEMENT

James A. Stricklin*, Walter E. Haisler**, Patrick R. Tisdale⁺, and Richard Gunderson Texas A&M University
College Station, Texas

Finite elements have been developed for the analysis of plane stressplane strain problems¹, bodies of revolution², and shells of revolution^{3,4}.

However, considerable difficulties have been encountered in the development of suitable plate and shell elements. These difficulties are caused by the need for both displacement and slope compatibility along the lines connecting the elements which in turn is caused by the dependence of the internal energy on the second derivatives of the normal displacement. One way to avoid the need for compatibility of first derivatives is to include transverse shear deformations thus yielding a strain energy expression as a function of the first derivatives only. This approach has been used in Refs. 5, 6, and 7. However, those researchers used linear functions for all variables which yields a solution which converges slowly with mesh refinement. The purpose of this note is to present a compatible triangular plate element based on a complete third order polynomial for the normal displacement and second order polynomials for the inplane displacements. A nine degree of freedom element

Research supported under Sandia Contract 82-2930 (SC-CR-68-3561) and NASA Grant NGL 44-001-044

^{*}Professor, Department of Aerospace Engineering

^{**}Research Assistant, Department of Aerospace Engineering

Research Assistant, Department of Aerospace Engineering
Assistant Professor, Department of Civil Engineering

is obtained by requiring the transverse shear deformations to be zero at the nodes and along the sides of the element.

Consider a laminate of thickness dz located at a distance z from the midsurface of the plate (Fig. 1). The displacements of this laminate are represented by

$$\mathbf{u} = \mathbf{z} \left[\mathbf{L}_{1} (2\mathbf{L}_{1} - 1) \frac{\partial \mathbf{u}_{1}}{\partial \mathbf{z}} + \mathbf{L}_{2} (2\mathbf{L}_{2} - 1) \frac{\partial \mathbf{u}_{2}}{\partial \mathbf{z}} + \mathbf{L}_{3} (2\mathbf{L}_{3} - 1) \frac{\partial \mathbf{u}_{3}}{\partial \mathbf{z}} \right]$$

$$+ 4L_{1}L_{2} \frac{\partial u_{4}}{\partial z} + 4L_{2}L_{3} \frac{\partial u_{5}}{\partial z} + 4L_{1}L_{3} \frac{\partial u_{6}}{\partial z} \right]$$

(1)

$$w = L_{1}^{2}(L_{1}+3L_{2}+3L_{3})w_{1} + L_{1}^{2}(c_{3}L_{2}-c_{2}L_{3}) \frac{\partial w_{1}}{\partial x} + L_{1}^{2}(b_{2}L_{3}-b_{3}L_{2}) \frac{\partial w_{1}}{\partial y} + \dots + \alpha L_{1}L_{2}L_{3}$$

where u, v, w = displacements in x, y, and z directions respectively

$$L_1$$
, L_2 , L_3 = area coordinates (Ref. 8)
 b_i = $y_j - y_k$
 c_i = $x_k - x_j$
 α = generalized coefficient

The expression for v is of the same form as the expression for u. The additional six terms in the expression for w are obtained by cyclic permutation.

A nine degree of freedom element is obtained by requiring the transverse shear strains to be zero at the corners and along the sides of the element and, by assuming the slope normal to the element at the middle of the side is one-half the sum of the values at the corner nodes. These conditions yield

$$\frac{\partial w_{i}}{\partial x} = -\frac{\partial u_{i}}{\partial z}$$

$$i = 1, 2, 3$$

$$\frac{\partial w_{i}}{\partial y} = -\frac{\partial v_{i}}{\partial z}$$

$$\frac{\partial u_{4}}{\partial z} = \frac{1}{b_{3}^{2} + c_{3}^{2}} \left[\frac{3}{2} c_{3}w_{1} + (\frac{b_{3}^{2}}{2} - \frac{c_{3}^{2}}{4}) \frac{\partial u_{1}}{\partial z} + \frac{3b_{3}c_{3}}{4} \frac{\partial v_{1}}{\partial z} \right]$$

$$-\frac{3}{2} c_{3}w_{2} + (\frac{b_{3}^{2}}{2} - \frac{c_{3}^{2}}{4}) \frac{\partial u_{2}}{\partial z} + \frac{3b_{3}c_{3}}{4} \frac{\partial v_{2}}{\partial z} \right]$$

$$\frac{\partial v_{4}}{\partial z} = \frac{1}{b_{2}^{2} + c_{3}^{2}} \left[-\frac{3}{2} b_{3}w_{1} + \frac{3}{4} b_{3}c_{3} \frac{\partial u_{1}}{\partial z} + (\frac{c_{3}^{2}}{2} - \frac{b_{3}^{2}}{4}) \frac{\partial v_{1}}{\partial z} + \frac{3}{2} b_{3}w_{2} + \frac{3}{4} b_{3}c_{3} \frac{\partial u_{2}}{\partial z} + (\frac{c_{3}^{2}}{2} - \frac{b_{3}^{2}}{4}) \frac{\partial v_{2}}{\partial z} \right]$$
The equations for $\frac{\partial u_{5}}{\partial z}$, $\frac{\partial v_{5}}{\partial z}$, $\frac{\partial u_{6}}{\partial z}$, and $\frac{\partial v_{6}}{\partial z}$

are obtained by cyclic permutation. Interelement compatibility is still satisfied after Eqs. 2 are applied.

Neglecting the strain energy due to transverse shear the strain energy expression for the element is the same as that used in plane stress problems.

$$U = \frac{E}{1-v^2} \int (\varepsilon_x^2 + \varepsilon_y^2 + 2v\varepsilon_x \varepsilon_y + \frac{1-v}{2} \varepsilon_{xy}^2) dAdz$$
 (3)

where E = Young's modulus

v = Poission's ratio

$$\varepsilon_{\rm x} = \frac{\partial {\rm u}}{\partial {\rm x}}$$

$$\varepsilon_{\mathbf{y}} = \frac{\partial \mathbf{v}}{\partial \mathbf{y}}$$

$$\varepsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$$

It is noted that w does not enter the strain energy expression but enters through Eqs. 2. The element stiffness matrix is obtained by substituting the assumed displacement functions into the strain energy expression and integrating over the volume of the element using the relation 9

 $\int L_{1}^{i} L_{2}^{j} L_{3}^{k} dA = \frac{i!j!k!}{(n+2)!} 2A$ (3)

where n = i + j + k

A = area of element

The element stiffness matrix is symmetric and positive definite.

The accuracy of this element representation is demonstrated by solving simply supported and clamped plates under uniform and concentrated loadings. For the uniform pressure loading one-third of the total load was allocated to each displacement at the corners of the element. The plate idealization is shown in Fig. 2 and the results for the deflection coefficients at the center of the plate are presented in Table 1. It is noted that the basic element

listed as QQ3 (quadratic u - quadratic v-third order w) is a little soft. The results listed as QQ3-3 were obtained by dividing the original element into three sub-elements with an internal node at the centroid of the original element. This gives a nine degree of freedom element with zero transverse shear along the sides and along the lines from the corners to the centroid. It is noted that the convergence characteristics of the QO3-3 element are quite good.

REFERENCES

- 1. Turner, M.J., Clough, R.W., Martin, H.C., and Topp, L.J., "Stiffness and Deflection Analysis of Complex Structures," Journal of Aeronautical Sciences, Vol. 23, No. 9, Sept. 1956, pp. 805-823.
- 2. Wilson, E.L., "Structural Analysis of Axisymmetric Solids," AIAA Journal, Vol. 3, No. 12, Dec. 1965, pp. 2269-2274.
- 3. Grafton, P.E. and Strome, D.R., "Analysis of Axisymmetrical Shells by the Direct Stiffness Method," AIAA Journal, Vol. 1, No. 10, Oct. 1963, pp. 2342-2347.
- 4. Stricklin, J.A., Navaratna, D.R. and Pian, T.H.H., "Improvements on the Analysis of Shells of Revolution by the Matrix Displacement Method," AIAA Journal, Vol. 4, No. 11, Nov. 1966, pp. 2069-2072.
- 5. Utku, S., "Stiffness Matrix for a Triangular Sandwich Element of Nonzero Gaussian Curvature," AIAA Journal, Vol. 5, No. 9, Sept. 1967, pp. 1659-1668.
- 6. Martin, H.C., "Stiffness Matrix for a Triangular Sandwich Element in Bending," Technical Report No. 32-1158, Feb. 1968, Jet Propulsion Laboratory, Pasadena, California.
- 7. Melosh, R.J., "A Flat Triangular Shell Element Stiffness Matrix," Technical Report 66-80, Dec. 1965, Air Force Flight Dynamics Laboratory, Wright-Patterson Air Force Base, Ohio, pp. 503-514.
- 8. Zienkiewicz, O.C. and Cheung, Y.K., The Finite Element Method in Structural and Continuum Mechanics, McGraw-Hill Pub. Co. Lim., New York, 1967, pp. 99-100.
- 9. Stricklin, J.A., "Integration of Area Coordinates in Matrix Structural Analysis," To be published in AIAA Journal.
- 10. Tocher, J.L. and Kapur, K.K., "Comment on Basis for Derivation of Matrices for the Direct Stiffness Method," AIAA Journal, Vol. 3, No. 6, June 1965, pp. 1215-1216.
- 11. Timoshenko, S. and Woinowsky-Krieger, S., <u>Theory of Plates and Shells</u>, McGraw-Hill Book Co., New York, 2nd Edition, 1959.

TABLE I

Deflection Coefficients For Square Plate

Mesh Size	Simply Supported Plate						Clamped Plate					
	Uniform Pressure			Concentrated Load			Uniform Pressure			Concentrated Load		
	QQ3	QQ3-3	Ref. 10	QQ3	QQ3-3	Ref. 10	QQ3	QQ3-3	Ref. 10	QQ3	QQ3-3	Ref. 10
2×2	.004162	.003666	.003446	.01248	.01100	.01378	.001890	.001533	.001480	.005669	.004598	.0 05919
4x4	.004056	.003942	.003939	.01169	.01128	.01233	.001547	.001452	.001403	.005856	.005506	.006134
6x6	.004064	.004012	محن على عبد حب سنة عبد عبد	.01165	.01145		.001406	.001357		.005763	.005569	
8x8	.004065	.004036	.004033	.01163	.01152	.01183	.001347	.001318	.001304	.005708	.005587	.005803
10×10	.004065	.004046		.01163	.01155	denis saled street spring street disable	.001319	.001299		.005678	.005596	
12x12	.004064	.004051	.004050	.01162	.01157	.01172	.001303	.001289	.001283	.005660	.005601	.005710
14×14	.004064	.004054	-	.01162	.01157		.001293	.001283		.005649	.005604	
16×16	.004064	.004056	.004056	.01161	.01158	.01167	.001287	.001279	.001275	.005641	.005606	.005672
Exact (Ref. 11)		.00406			.011.60			.00126			.00560	

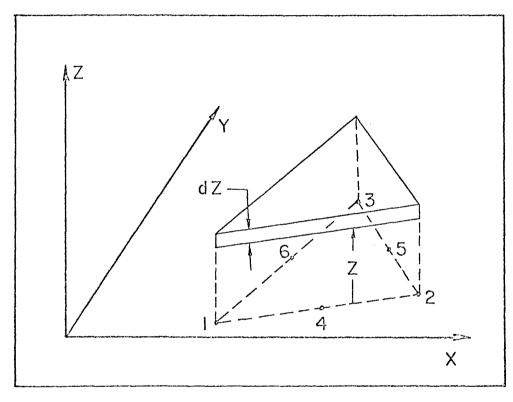


FIG. I ELEMENT LAMINATE AND NODES

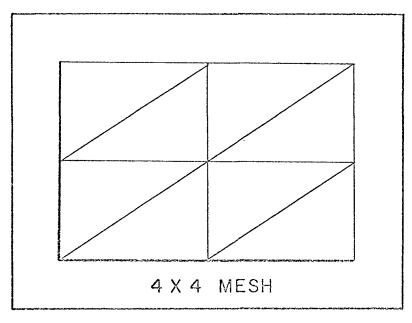


FIG. 2 PLATE IDEALIZATION FOR QUARTER OF A PLATE